Execution of UML Models with CPN Tools for Workflow Requirements Validation

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Abstract. Requirements validation is a critical task in any engineering project. The confrontation of stakeholders with static requirements models is not enough, since stakeholders with non computer science education are not able to discover all the inter-dependencies between the elicited requirements. Even with simple UML (unified modelling language) requirements models it is not easy for the development team to get confidence on the stakeholders’ requirements validation. This paper describes an approach, based on the construction of executable interactive prototypes, to support the validation of workflow requirements, where the system to be built must explicitly support the interaction between people within a pervasive cooperative workflow execution. A case study from a real project is used to illustrate the proposed approach.

1. INTRODUCTION

Clients (normally, stakeholders) and developers (system designers and requirements engineers) have, naturally, different points of view towards requirements. A requirement can be defined as “something that a client needs” and also, from the point of view of the system designer or the requirements engineer, as “something that must be designed”. The IEEE 610 standard [1] defines a requirement as: (1) a condition or capability needed by a user to solve a problem or achieve an objective; (2) a condition or capability that must be met or possessed by a system or system component to satisfy a contract, standard, specification or other formally imposed documents; (3) a documented representation of a condition or capability as in (1) or (2).

Taking into account these two distinct perspectives, two different categories for requirements can be conceived:

- **User requirements** result directly from the requirements elicitation task [2], as an effort to understand the stakeholders’ needs. They are, typically, described in natural language and with informal diagrams, at a relatively low level of detail. User requirements are focused in the problem domain and are the main communication medium between the stakeholders and the developers, at the analysis phase.

- **System requirements** result from the developers’ effort to organize the user requirements at the solution domain. They, typically, comprise abstract models of the system [3], at a relatively high level of detail, and constitute the first system representation to be used at the beginning of the design phase.

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The correct derivation of system requirements from user requirements is an important objective, because it assures that the design phase is based on the effective stakeholders’ needs. Some existent techniques [4-7] can be used to support the transformation of user requirements models into system requirements models, by manipulating the corresponding specifications. This also guarantees that no misjudgement is arbitrarily introduced by the developers during the process of system requirements specification.

However, this effort of maintaining the model continuity by applying transformational techniques can prove to be worthless, if the user requirements models are not effectively validated. Typically, the confrontation of stakeholders with static requirements models is not enough, since stakeholders with non computer science education are not able to discover all the inter-dependencies between the elicited requirements. Even with simple UML requirements models (use case diagrams and some kind of sequence diagrams) it is not easy for the development team to get confidence on the stakeholders’ requirements validation. In fact, according to [8] there are three kinds of analysis that should be accomplished before a workflow is put into production: (1) validation, to check if the workflow behaves as expected; (2) verification, to study the correctness of a workflow; (3) performance analysis, to estimate the solution conformance with throughput times, service levels, and resource utilization. This paper is solely devoted to the first kind of analysis at the process level, i.e., we are neither considering the resource dimension where resources estimation is supposed to be reached, nor the case dimension where a concrete instance of a workflow process is analysed both in its commonalities and exceptions.

This paper describes the usage of CPN Tools [9] in the generation of interactive prototypes to allow stakeholders to be confronted with executable versions of previously elicited UML use case and sequence diagrams. This approach towards user requirements validation is illustrated with a real case study where a healthcare information system must be built to explicitly support the interaction between people within a pervasive workflow execution.

The remaining of this paper is organized as follows. Section 2 presents the case study by informally describing the purposes of the uPAIN system. Some UML models of the uPAIN system are also presented to support the discussion on the difficulties of achieving effective requirements validation based on static user requirements models. In section 3, we describe the construction of coloured Petri nets for animation of the dynamic properties of UML models. Here, the relation between the adopted stereotyped UML sequence diagrams and the coloured Petri nets is explained. Section 4 contains the global architecture of the tool environment used to generate the interactive animation prototype. Since some interoperability issues are not technological transparent when CPN Tools are used together with the BRITNeY Animation tool, some examples of the required XML files to perform the integration are discussed. In section 5, the strategies used to design the graphical user interface of the interactive animation prototype are discussed and some usability issues are referred. This section is devoted to the discussion of the efforts that must devote to obtain an animation artefact that effectively involves the stakeholders in the workflow requirements validation. Section 6 concludes the paper with some final remarks, mainly devoted to the
synthesis of the proposed approach limitations and of the accomplishments achieved. Future work is also briefly referred.

2. REQUIREMENTS MODELING

The case study considered in this paper consists of an information system (uPAIN system) whose main concern is the process of pain control of patients in a hospital, who are subjected to relatively long periods of pain during post surgery recovery. When a surgery is concluded, the patient enters a recovery period, during which analgesics must be administered to him in order to minimize the pain that increases as the effects of the anaesthesia gradually disappear. This administration of analgesics must be controlled according to a program which depends on factors like some personal characteristics of the patient (weight, age …) and the kind of surgery to which the patient has been submitted. The quantity of administered analgesics must be high enough to eliminate the pain, but low enough to avoid exaggerated or dangerous sedation states. This controlled analgesia is supplied to the patient by means of specialized devices called PCAs (patient controlled analgesia). PCA is a medication-dispensing unit equipped with a pump attached to an intravenous line, which is inserted into a blood vessel in the patient’s hand or arm. By means of a simple push-button mechanism, the patient is allowed to self administer doses of pain relieving medication (narcotic) on an “as need” basis. This is called a bolus request.

The motivation for the development of the uPAIN system arises from the fact that different individuals feel pain and react to it very differently. Also, although narcotic doses are predetermined as mentioned previously, there is a considerable variability of their efficiency from patient to patient. This is why anaesthesiologists are interested in monitoring several variables, in a continuous manner during patients’ recovery, in order to increase their knowledge on what other factors, besides those already known, are relevant to pain control, and in what measure they influence the whole process. To achieve this, the main idea behind the uPAIN system is to replace the PCA push-button by an interface on a PDA (personal digital assistant), which still allows the patient to request doses from the PCA, but with the addition of the functionality of creating records in a database of all those requests, along with other data considered relevant by the medical doctors, like the values of some pre-determined physiological indicators measured by a monitor, and/or other data related to a particular patient’s state, symptoms, etc. These questions may be automatically asked by the system, via the PDA, when the patient requests a dose or at regular time intervals, or even when a medical doctor decides to ask for it.

So, the uPAIN system is intended to provide a platform that enables the registration of patients’ pain levels and the occurrence of several symptoms related with analgesia processes, as frequently as desired, while allowing the medical staff to be permanently aware of the occurrence of all the relevant facts of the patients’ recovery and pain control processes and, simultaneously, allowing permanent remote wireless communication among system, patients and medical staff.

Requirements elicitation is all about learning and understanding the needs of users and project sponsors with the ultimate aim of communicating these needs to the system developers [2]. Getting the right requirements is considered as a vital and difficult part of soft-
ware development projects. Modelling and model-driven approaches provide ways of representing the existing or future processes and systems using analytical techniques with the intention of investigating their characteristics and limits [3].

UML use case diagrams are a quite adequate tool to describe user requirements at a first high-level of abstraction. These diagrams constitute a suitable means for delimiting the system boundaries, for identifying the functionalities that should be provided by the system, and for affecting external actors with specific use case functionalities. Additionally, brief textual descriptions may be provided in natural language for each use cases. These diagrams are normally constructed by the developers in a tentative to document the elicited requirements. Stakeholders can read and use these diagrams to recognize the main functional areas of the system to be designed.

General functionalities of the uPAIN system are inscribed in the UML use case diagram depicted in Fig. 1. A set of additional use case diagrams have been constructed to refine some of the use cases existent in Fig. 1. The corresponding textual descriptions have also been obtained.

With the exception of just a few «uses» and «extends» relationships that may already be shown between use cases, it turns out to be obvious that use case diagrams do not practically say anything about how the system should be designed, in order to supply the identified functionalities. A further step on that direction may be provided by sequence diagrams in order to illustrate the desired dynamic behaviour in what concerns its functional interaction with the environment. These diagrams are also to be constructed by the developers. Stakeholders can also read them. However, they are not comfortable with all the details these diagrams can entail.

Fig. 2 depicts one UML sequence diagram for the uPAIN system that describes one macro-scenario where a patient requests a bolus. That request may be accepted by the system or originate a request for an explicit medical decision. In the later case, the
doctor may decide to authorize the bolus or to reconfigure the PCA parameters. The integration of several scenarios into only one sequence diagram (for a macro-scenario) is possible due to the new mechanisms of UML 2.0 in supporting different kinds of frames.

Some more UML sequence diagrams have been constructed to capture the main system scenarios. At the analysis phase of system development, we adopt a stereotyped version of UML sequence diagrams, where only actors and use cases are involved in the sequences, since no particular structural elements of the systems are known yet. This kind of sequence diagrams allow a pure functional representation of behavioural interaction with the environment and are particularly appropriate to illustrate workflow user requirements.

Our stereotyped UML sequence diagrams contrast with the traditional ones that already involve system objects in the interaction with external actors, implying that those objects must be previously identified. One important issue concerning objects identification and building object diagrams is that they already model structural elements of the system, which is clearly beyond the scope of the user requirements. Additionally, the use of this kind of traditional sequence diagrams at the first stage of analysis phase (user requirements modelling and validation) require a deeper intervention of modelling skills that are hardly understandable to most stakeholders, making more difficult for them to establish a direct correspondence between what they initially stated as functional requirements and what the model already describes. So, a validation of the user requirements resulting from such an advanced model is not only
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more difficult to achieve, but also less trustworthy and less ensuring that the resulting system will correspond effectively to the stakeholders expectations.

3. CPNs FOR ANIMATION PROTOTYPES

The effort to use only elements from the problem domain (external actors and use cases) in the user requirements models (use case and stereotyped sequence diagrams) and to avoid any reference to elements belonging to the solution domain (objects and methods) is not enough to obtain requirements models that are capable of being fully understandable by common stakeholders. This difficulty is mainly observable in what concerns the comprehension of the dynamic properties of the system within its interaction with the environment. This means that, even with the referred efforts, those static requirements models should not be used to directly base the validation of the elicited user requirements by the stakeholders. Instead, we use those static requirements models to derivate animation prototypes.

User friendly visualizations of the system behaviour, automatically translated from formal systems’ models specifications, accepting user interaction for validation purposes, have been generically called animations. Despite seeming a good idea, in a context where IT is offering more and more powerful multimedia capabilities, the use of animation in user requirements validation, as a means of improving the understandability of systems’ models by stakeholders, has been considered by only a small number of researchers.

In [10] an empirical study has been carried out to comparatively evaluate the effectiveness of animation and narration (voice recordings of diagram explanations complemented with PowerPoint slides) in the process of communication of domain information to stakeholders for validation purposes, which may be seen as a sign that animation is increasingly drawing the software engineers’ attention as a potentially valuable instrument for user requirements validation. The results of that empirical study were inconclusive about the effectiveness of animation, as opposed to the success of narration, but in our opinion that was due to the fact that, instead of using a meaningful user interface, the animations were of a very rudimentary type by highlighting the graphical elements of the diagrams while narration is being executed.

Some other papers have been published, reporting the use of animations to ease validation by stakeholders, as is the case in [11], where a CORBA API has been used to directly interpret VDM-SL specifications of requirements to generate a graphical user interface. Scenario-based approaches have also been used in [12] as a means of ensuring user-orientation, and also in [13], where fluents (boolean system states that model pairs of system actions) have been used to relate goals with scenarios and, simultaneously, support animation. In [14], virtual reality is used to support animation techniques when modelling high consequence systems (systems where errors in development have consequences of high cost).

The behaviour of the animation prototypes (proposed in this paper) results from rigorous translations of the sequence diagrams into Coloured Petri Nets (CPNs) [15, 16]. The transitions of these CPNs present a strict one-to-one relationship with the messages in the sequence diagrams. So, for each message in a sequence diagram, one transition, in the corresponding CPN, is created. The name of each transition matches
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exactly the corresponding name of the message in the sequence diagram. Two simple rules were used for that translation: (1) Fig. 3 illustrates the rule for translating two successive messages in a sequence diagram (Fig. 3a) into a CPN (Fig. 3b); (2) Fig. 4 illustrates the rule for translating an alternative block in a sequence diagram (Fig. 4a) into a CPN (Fig. 4b).

Fig. 3. Transformation of successive messages.

Fig. 4. Transformation of an alternative block.

Each output place of a transition (corresponding to a message in a sequence diagram that ends in a life line of a use case) represents the reaction of the system to the message request. Although CPN Tools do not support the creation of pages for the addition of refinement subnets for places (that is the reason why we use the expression “refinement subnets”, instead of “refinement subpages”), those output places may be replaced, at the same hierarchy level, by refinement sub-nets (composed of one input place, one output place, and one substitution transition between them) to support the refinement of use cases. The refinement subpage for each substitution transition describes one refined use case.

Typically, the refinement subnets will be built after the application of the 4SRS (4 step rule-set) technique [7] that transforms users requirements into architectural models representing system requirements, by mapping use cases into system-level objects within a four step approach: (1) object creation, (2) object elimination, (3) object packaging and aggregation, and (4) object association. Therefore, each transition in those subnets will correspond to the invocation of a method of a system object.
The CPN of Fig. 5 is responsible for the animation of the use case \{U0.1\} administer drug (see Fig. 1) by executing three different sequence diagrams, each one corresponding to one of the three branches of the CPN. The middle branch is responsible for the execution of the sequence diagram of Fig. 2. Those nodes and arcs drawn with thinner lines were added in a later phase, and have no semantic correspondence to the sequence diagrams. They were included for the purpose of tools interoperability, as explained in section 4.

The CPN represented in Fig. 6 corresponds to the top-level net of the animation prototype for the uPAIN system. Thick lines were used to represent the elements that correspond to the main animation paths. Most of the transitions of this CPN
correspond to the use cases in Fig. 1. The refined CPN of the substitution transition bolus request of Fig. 6 corresponds to Fig. 5.

![Top-level CPN of the animation prototype for the uPAIN system.](image)

**Fig. 6.** Top-level CPN of the animation prototype for the uPAIN system.

With the transformation rules depicted in Fig. 3 and Fig. 4, direct links between the use case diagram (Fig. 1) and the CPNs (Fig. 5 and Fig. 6) are not intended, nor considered of interest. Instead, the link between the UML diagrams and the CPNs is obtained in two steps: the first is supported by the fact that the sequence diagrams are directly derived from the use cases; the second is ensured by a direct transformation of the sequence diagrams into CPNs.

Sequence diagrams transmit partial views for the interaction between the system and its environment, allowing the adoption of an evolutionary approach, by considering a set of sequence diagrams to have a partial evaluation of the requirements and then progress with more detailed requirements. In the uPAIN system, the animation prototype reflects only a top-level description of the system. After the validation of this top-level model, a set of additional animations, based on refined sequence diagrams at the solution level (where objects would already appear), can be constructed.
4. TOOLS INTEGRATION

The implementation of the interactive animation prototype demanded the usage of several technologies. The integration of tools was mainly based on XML files. Fig. 7 shows the global architecture of the tool environment used to generate the animation prototype. It is composed of a model executor and an animation tool. The model executor includes a CPN editor and a CPN simulator, both from CPN Tools. The animation tool used corresponds to the BRITNeY Animation tool [17].

With BRITNeY Animation tool it is possible to use pre-defined plug-ins (or write our own plug-ins) for executing some animation behaviour in the model. The pre-defined plug-ins include SceneBeans [18] (an animation framework), message sequence charts (for displaying the passing of messages) and plot graphs. The writing of our own plug-ins involves the coding of Java classes and the creation of an XML description of the plug-in. BRITNeY Animation tool will automatically generate the code needed for the simulator to know of and use those plug-ins.

It is possible to execute behaviours in the BRITNeY Animation tool while simulating models in CPN Tools. Behaviours are executed through certain SML functions which in turn call the corresponding Java methods. The names of the functions correspond to those of the Java methods. When an SML function calls a Java method it simply corresponds to the logic of an RMI call. The method name and arguments are passed over to the interface of the BRITNeY Animation tool and the return value of the executed method is passed back from the interface. If the method $M$ in class $C$ has the signature $\text{int } M(\text{int } x, \text{string } y)$, then it could be invoked as $C.M(42, \text{"Hello World"})$. However, this is just an example to explain the way to use the Java methods in the CPN model (see [17] for complementary explanations). These behaviours, or methods, can be executed anywhere in the CPN model where an expression is allowed. So, it can be on an arc expression, code segments on transitions (these are specific for CPN Tools), and so on.
This is a nice feature for debugging and for understanding the way the model affects the animation.

The BRITNeY Animation tool can also be executed as a standalone program, using e.g. Java WebStart to enable web browser integration. This feature is very useful to generate an autonomous animation prototype which allows stakeholders to “play with” without the interference and the presence of elements from the development team. This approach to validation was experimented with and proved to be very effective. This empowerment of the stakeholders promoted a deeper involvement of them in the analysis phase that not only assured better validation results, but also allowed the complementary elicitation of workflow requirements.

The interactive animation prototype for the uPAIN system is depicted in Fig. 8. The usage of SceneBeans allowed the animation of actors and message passing. SceneBeans provides a parser that translates XML documents into animation objects. A SceneBeans document is contained within a top-level <animation> element that contains five types of sub-elements: (1) a single <draw> element defines the scene graph to be rendered (e.g. the representation of the doctor, the nurse, the patient); (2) <define> elements define named scene graph fragments that can be linked into the visible scene graph; (3) <behaviour> elements define behaviours that animate the scene graph (e.g. the animation of the drug injection from PCA to the patient); (4) <event> elements define the actions that the animation performs in response to internal events (e.g. the cleaning of the info text at the end of the drug injection animation); (5) <command> elements name a command that can be invoked upon the animation and define the actions taken in response to that command (e.g. the invocation of the behaviours responsible for the drug injection animation).

Fig. 9 shows an example of a code segment that was used in our <draw> element. This code segment is responsible for the creation of the icons for the patient, the uPAIN system and the black ball that represents the messages between actors. To animate the ball, we used the <animate> element, that means that parameters \( x \) and \( y \) will be animated by the behaviours \( \text{xf\_patient\_to\_system} \) and \( \text{yf\_patient\_to\_system} \), respectively.

Fig. 10 shows the behaviours, the commands and the events that are responsible for moving the ball from the patient to the uPAIN system. When the simulator invokes the command \( \text{f\_patient\_to\_system\_cmd} \), the behaviours corresponding to the movement of the ball and the displaying of its textual info are started. When the execution of a behaviour ends, the animation will trigger the associated event, and this will start other behaviours, like \( \text{xball\_out} \) (to hide the ball), \( \text{fadeout\_info} \) (to hide the textual info), or \( \text{hide\_patient\_pda\_icon} \) (to hide the patient PDA icon). At the end, the event will be announced, which is crucial, because it allows the CPN simulator to capture it.

Communication between SceneBeans objects in the animation and the CPN model can be done in two ways: (1) asynchronously, here the CPN model simply invokes a command on a SceneBeans object and proceeds simulating, not caring for the moment when the animation behaviour that was executed terminates; (2) synchronously, here the CPN model, again, invokes a command on a SceneBeans object, but, instead of just proceeding, the CPN model waits for a particular event to arrive (e.g. the event “ball moved from patient to system”). This event would be broadcasted by the animation command that was executed when it terminates to let the CPN model know that this animation has completed. Synchronous interactions with SceneBeans objects must be
carefully analyzed; otherwise, animations that should be executed in sequence will be executed concurrently. It is necessary to determine which animation behaviours are to be completed before any other can proceed (synchronous) and those which can occur in any order (asynchronous). Invocations on SceneBeans objects are asynchronous in the sense that, per default, they do not broadcast any event; this has to be specified in the SceneBeans XML specification.

Fig. 8. Interactive animation prototype for the uPAIN system.

After creating all the behaviours, commands and events, which allow the animation to announce events and receive commands from the CPN simulator, the next step is to create Java classes. SceneBeans have the limitation of not allowing the user to input dynamic contents. In fact, SceneBeans only allows the creation of animations, based on static behaviours, defined in an XML file. The Java classes we created are responsible for showing the graphical interfaces of the PDAs and for sending the corresponding user (of the animation prototype) inputs to the CPN simulator. For instance, the Log Window that shows all the messages sent between actors demanded the creation of a Java class (Messenger) that receives the messages from the CPN simulator. To add a new message to the list of messages of the Log Window, we simply invoke Messenger.createAndShowGUI("message"). After creating the Java classes, an XML description must be constructed so that the BRITNeY Animation tool recognizes them as plug-ins (see Fig. 11).
To access public methods of previously written Java classes (Chat, ScenarioSelector, Messenger, Ppda, Dpda, and Npda) and to invoke commands of the SceneBeans object (object anim) from the CPN Tools, plug-ins must be declared and instantiated as objects in the index of CPN Tools (see Fig. 12).
Java classes in defined animation plug-ins can be instantiated through SML (Standard Meta Language) functors that BRITNeY Animation tool generates. SML functors are “abstract” SML structures which can be instantiated. A Java object is instantiated by, e.g.,  
\[ \text{structure anim = SceneBeans(val name = "Name")}, \]  
which instantiates an object from the SceneBeans class. Methods on the instantiated \( \text{anim} \) are accessed as public methods defined in the SceneBeans class. Another example is the function \( \text{SPO()} \) in the transition Select Patient Options of Fig. 6 that contains the following code to invoke methods to our Java objects:

\[
\begin{align*}
&\text{Messenger.cleanText();} \\
&Ppda.createAndShowGUI("mainmenu"); \\
&Ppda.getValueString(); \\
\end{align*}
\]

SceneBeans objects provide also some methods to control the animation. For instance, the calling of function \( \text{move()} \) in the CPN of Fig. 5 consists in an invocation of the method \( \text{invokeCommand} \) to the SceneBeans object \( \text{anim} \) (Fig. 12), which is responsible for invoking the previously defined commands in the XML file (Fig. 10). In this case, the invoked command corresponds to the movement of the black ball between the actors of the animation.

\[
\text{Fig. 11. Defining Java classes as plug-ins of BRITNeY Animation tool.}
\]

Additionally, it is possible to capture events announced by the animation. In our animation prototype we included one CPN subpage called Events (Fig. 13) that is composed by two distinct parts: one is responsible for the initial loading of the XML animation description (places Start and Running, and transition Init); the other part includes the transition Capture Event (captures all the events announced by the SceneBeans animations and places them, in the form of a string list, in the place Events) and the place Events. This place Events can be cloned and connected to any transition where the capture of specific events is required (see, for instance, the nodes and arcs drawn with thinner lines in Figs. 5-6). These cloned places are named EventN (where \( N \) is a digit that serves only as a distinguishing character, because CPN Tools do not accept places with the same name, in the same page) and have no semantic meaning from the workflows’ point of view. They are only needed for tool interoperability.
Fig. 12. Declaring and instantiating objects in CPN Tools.

Fig. 13. Events CPN subpage.

5. USABILITY ISSUES

According to [19], usability is considered “the extent to which a product can be used by specified users to achieve specified goals with effectiveness, efficiency and satisfaction in a specified context of use”. This means that, besides all the technical efforts described in the previous two sections of this paper, the effectiveness of the implemented animation prototype to involve stakeholders in the interactive execution of the elicited sequence diagrams, complementary elicitation of workflow requirements and validation of the requirements model was also a result of a strong investment in using usability techniques in the construction of this software artefact, namely in what concerns its GUI (graphical user interface) and the comfort of exploitation of the animation prototype.

The adopted GUI makes use of eight icons on the display: three proactive actors (one patient, one medical doctor and one nurse); four reactive actors (one monitor, one PCA device and two databases in use at the hospital); and the uPAIN system represented by a cloud. The adopted GUI should be obvious and intuitive to the
stakeholders and thus, with the exception of the cloud and the databases, we opted for “concrete” icons. When real-world objects are represented in an icon (“concrete” icon), individuals are likely to find it more meaningful, are often familiar with the items depicted, and find it easy to make links between what is shown in the icon and the function it is supposed to represent [20]. To symbolize the uPain system (a concept which is difficult to materialize and to represent), we chose a cloud which constitutes an “abstract” icon. Forming strong systematic relations between icons and functions is very important, particularly when there are no pictorial alternatives for a given icon function [21]. To represent the uPain system we wanted an icon that emphasized its pervasive and wireless nature. Databases are also represented through an “abstract” icon which is a standard way to represent software-technology databases. We also opted for uniform icons in terms of size because we wanted to avoid stakeholders focusing on some of the icons and not others due to size differences; we wanted them to have, at the first glance, the notion of the whole GUI. On the other hand, the real sized PDA is the bigger element and the only one which detaches from the GUI in terms of size, in order to improve the legibility of its contents.

Fig. 14. Message passing in the animation prototype for the uPAIN system.

Whenever one proactive actor is clicked with the mouse, a PDA icon appears above it and then, a real sized version of the PDA is also displayed, showing the predefined options, corresponding to possible requests (see Fig. 8). Through each proactive actor’s PDA, the stakeholder just has to select the desired option and then the corresponding sequences are executed (each one of these is formally related with one of the UML stereotyped sequence diagrams).
Each time one of the proactive actors is clicked, a black ball (representing the actor’s request) is sent from the actor towards the cloud. In Fig. 14, the stakeholder interacting with the animation prototype chose the “consult patient state” option by using the PDA of the medical doctor. The snapshot in Fig. 14 corresponds to the exact moment in which the monitor is sending to the uPAIN system some physiological indicators about the patient; this data exchange is graphically represented by the black ball trajectory in the display. This snapshot also shows a log window, where all the requests and interactions are registered. At the same time, underneath the cloud, a textual expression “receiving patient data” identifies the ongoing request/interaction. A caption, identifying the selected option is displayed during the whole action in the upper left corner of the display to prevent stakeholders from forgetting the task at hand and to provide them feedback, a golden rule of GUI design suggested in [22]. It is crucial for stakeholders that the animation prototype lets them know at what point they are, at any given time in a clearly understandable way. Additionally, in Fig. 8 it is possible to observe a green coloured “Ready…” message informing that the animation prototype is ready to accept one mouse click in one of the buttons of the displayed PDA. If, in any point of the simulation, the actor “uPAIN system” is in processing state, then a spinning globe appears inside the cloud and a red coloured “Running…” message is presented (see Fig 12).

To assure that the purpose of any graphical entity is clearly apparent and inferred (an important cognitive dimension in GUI design to deal with expressiveness [23]), a green dashed line contour was added around each proactive actor to make clear that only these are the proactive actors on which it is possible to click to produce some kind of interaction (Fig. 15). The green coloured “Ready…” message also appears when these green dashed line contours are displayed. We also used a dashed line and different background colours to help delimit the three main areas of the GUI and grouping actors in a logical way, according to the areas in the hospital where they may be: the patient, the monitor and the PCA are always in the infirmary; the two databases are installed in the server’s room; the medical doctor and the nurse can be elsewhere due to the nature of uPain system (ubiquitous); and the uPain system is “everywhere” in the hospital and so the cloud is placed in the middle of the three dashed areas. Below each actor, and to ensure that the actor is clearly identified immediately, the respective caption was added, since good labelling can guide stakeholders through the GUI with minimal search time. We also labelled the three dashed areas. This approach in GUI design contributes for a reduced cognitive load and immediate recognition in detriment of recalling in order to let stakeholders make optimal use of their high level cognitive abilities and save them to perform the essence of work; i.e., using the high level cognitive capacity for the more demanding work tasks such as workflow requirements validation, which is the real aim of the animation prototype.

The reduction of short-term memory load [23] was another intended goal, once in that part of memory only few information elements (typically, 5 to 8) can be stored simultaneously and the decay time is short (approximately 15 sec.). Thus, we avoided a dense area with many elements and presented only the necessary information.
Fig. 15. Dashed line contours in the animation prototype for the uPAIN system.

The animation prototype was first demonstrated to the stakeholders with a strong involvement of the developers to explain the main approach to its usage as a software artefact to support the early execution of functional requirements. After that, the stakeholders have been given a standalone version of the animation prototype. This usage of the animation prototype has enabled the effective validation of requirements, since stakeholders generate frequently change requests to incorporate new scenarios and to adjust others already elicited, which has definitively contributed to the rapid evolution of the requirements model maturity, prior to design phase. We believe the usability concerns we adopted in designing the whole animation prototype was determinate to the success of the uPAIN project.

6. CONCLUSIONS

Static requirements models should not be used to directly base the validation of the elicited user requirements by the stakeholders, since the effort to use only elements from the problem domain in the user requirements models and to avoid any reference to elements belonging to the solution domain is not enough to obtain requirements models that are capable of being fully understandable by common stakeholders. The stakeholders’ comprehension of the dynamic properties of the system within its interaction with the environment is better assured if animation prototypes, formally deduced from the elicited static requirements models, are used.

The behaviour of the animation prototypes can be specified by using CPNs rigorously translated from use case and stereotyped sequence diagrams. An effective execution of UML models can be achieved by using CPN Tools to operationally imple-
ment the interaction with the stakeholders within their efforts to validate the previously elicited workflow requirements models. Presently, the referred transformations are executed manually, which can be considered a major drawback of the proposed approach when the system to animate is of large dimension, presenting a great number of use cases and a large amount of behavioural scenarios to transform into CPNs.

The generation of standalone versions of the interactive animation prototypes motivates stakeholders to get a deeper involvement in the analysis phase (without the interference of the development team). Usability features of the animation prototypes must also be carefully studied and experimented, before reaching the final version of the prototype in supporting the interactive execution of the elicited sequence diagrams, complementary elicitation of workflow requirements and validation of the requirements models. CPN Tools and BRITNeY Animation tool should evolve to support better the transparent generation of this kind of standalone versions and to allow a simpler start-up of an animation.

As future work, we intend to automatically generate CPN skeletons from workflows requirements models (use case and stereotyped sequence diagrams). Additionally, we will study the possibility of using CPNs, constructed for specifying the behaviour of the animation prototype, to base the behavioural specification of the elements that will compose the architecture of the system within the design phase. If data-flow languages (such as LabVIEW, as described in [24, 25]) are used to develop the semantic layer responsible for integrating the whole ubiquitous system (embedded and mobile devices, database accesses and a service-oriented architectural platform), the asynchronous nature of CPNs will smooth the transition from analysis to design phases in what regards behavioural models. A semantic layer in the Arena environment [26], capable of accepting CPN-based workflow specifications, will also be developed to allow the stochastic execution of workflow scenarios as a complement to the current validation approach based on CPN Tools.

References

17. BRITNeY Animation tool. wiki.daimi.au.dk/tincpn