## ROBUST DISTRIBUTED DATA AGGREGATION

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Distributed Algorithms, Data Aggregation, Fault-Tolerance, Dynamic Networks.

## **ABSTRACT**

Data aggregation plays an important role in the design of scalable systems, allowing the determination of meaningful system-wide properties to direct the execution of distributed applications. In the particular case of wireless sensor networks, data collection is often only practicable if aggregation is performed. Several aggregation algorithms have been proposed in the last few years, exhibiting different properties in terms of accuracy, speed and communication tradeoffs. However existing approaches exhibit many dependability issues when used in faulty and dynamic environments. In this work, we propose a novel fault-tolerant averaging based data aggregation algorithm: Flow Updating. The algorithm is based on manipulating flows (in the graph theoretical sense), that are updated using idempotent messages, providing it with unique robustness capabilities. Experimental results have shown that Flow Updating outperforms previous averaging algorithms in terms of time and message complexity, and unlike them it self adapts to churn without requiring any periodic restart, supporting node crashes and high levels of message loss.

## INTRODUCTION

Aggregation plays an important role on distributed systems, in particular to provide meaningful global properties (e.g. network size; total storage capacity; average load; or majorities), and direct the execution of decentralized applications. For instance, several network statistics and administration information can be obtained from aggregation mechanisms, like: the amount of resources available on the network, the average session time of a peer, or the average (maximum or minimum) network load.

In the particular case of Wireless Sensor Networks (WSN), aggregation techniques are essential to monitor and control the covered area, allowing the computation of diverse statistics, such as: the minimum/maximum temperature, the average humidity, measure the concentration of a toxic substance (e.g. carbon monoxide), the noise level, etc. Moreover, due to the

specific constraint found in WSN, data collection is often only practicable if aggregation is performed (to optimize and restrain energy consumption).

Robbert Van Renesse defined aggregation as "the ability to summarize information", stating that "it is the basis for scalability for many, if not all, large networking services" (Renesse, 2003). In a nutshell, data aggregation is considered a subset of information fusion, aiming at reducing (summarize) the handled data volume (Nakamura et al., 2007).

Distributed data aggregation becomes particularly difficult to achieve when faults are taken into account (i.e. message loss and node crashes), and especially if dynamic settings are considered (nodes arriving and leaving). Few have approached the problem under these settings (Madden et al., 2002; Li et al., 2005; Ganesh et al., 2007; Kostoulas et al., 2005; Jelasity et al., 2005; Kennedy et al., 2009), proving to be hard to efficiently obtain accurate and reliable aggregation results in faulty and dynamic environments.

A useful class of high accuracy aggregation algorithms is based on averaging techniques (Kempe et al., 2003; Jelasity et al., 2005; Chen et al., 2006; Wuhib et al., 2007). Such algorithms start from a set of input values spread across the network nodes, and iteratively average their values with neighbors. Eventually all nodes will converge to the same value and can estimate some useful metric. Averaging tech- niques allow the derivation of different aggregation functions besides average (like counting and summing), according to the initial combinations of input values. These techniques are thought to be robust and accurate (converge over time), when compared to other aggregation techniques, but in practice they exhibit relevant problems that have been overlooked, not supporting message loss nor node crashes, see (Jesus et al., 2009a) for more details.

We design a novel averaging based aggregation technique: Flow Updating. This new algorithm tolerates quite easily high levels of message loss and supports nodes node arrival and departure/crash. Moreover, our new technique achieves an improved convergence speed compared to previous approaches.

# FLOW UPDATING

Flow Updating is a novel averaging based aggregation algorithm, that enables the computation of aggregation functions (e.g. average, count or sum) over a distributed

system. It works over any network topology and tolerates faults. Like existing gossip-based approaches, it averages values iteratively during the aggregation process towards converging to the global network average. The algorithm departs from current approaches, that keep the current "mass" value in a variable and send "mass" in messages; in these approaches message loss implies mass loss and consequent deviation from the correct estimate.

The key idea in Flow Updating is to use the flow concept from graph theory (which serves as an abstraction for many things like water flow or electric current), and instead of storing in each node the current estimate in a variable, compute it from the input value and the contribution of the flows along edges to the neighbors.

The essence of the algorithm is: each node i stores the flow f(ij) to each neighbor j; node i sends flow f(ij) to j in a message; a node j receiving f(ij) updates its own f(ji) with -f(ij). Messages simply update flows, being idempotent; the value in a subsequent message overwrites the previous one, it does not add to the previous value. If the skew symmetry of flows holds, the sum of the estimates for all nodes (the global mass) will remain constant.

Enforcing the skew symmetry of flows along edges through idempotent messages is what confers Flow Updating its unique fault tolerance characteristics, that distinguish it from previous approaches. It tolerates message loss by design without requiring additional mechanisms to detect and recover mass from lost messages. It solves the mass conservation problem, not by instantaneous mass invariance, something impossible to achieve in a failure-prone distributed system, but by having *mass convergence*.

Flow Updating cope with node departure/crash and node arrival, simply by maintaining a dynamic mapping of flows according to the current set of neighbors: removing the entries relative to leaving (or crashing) nodes, and adding entries for newly arrived nodes.

More details about Flow Updating can be found in (Jesus et al., 2009b) and (Jesus et al., 2010), as well as some experimental results that evidence its fault-tolerant characteristics and it's better performance compared to other approaches.

#### **CONCLUSION**

We designed new distributed data aggregation approach: Flow Updating. Like existing average-based algorithms it allows the accurate computation of aggregates at all nodes, converging to the exact result along time, and working independently from the network routing topology. But unlike previous approachs, it is robust against message loss, overcoming the problem of "mass" loss verified on existing averaging algorithms. Moreover, it has shown to be able to adpat to changes of the network membership (churn) and supports node crashes.

Evaluation showed that Flow Updating clearly outperforms previous strategies, and unlike them it is fault tolerant and adapts to network changes in a continuous fashion without requiring protocol restarts. For more details see: (Jesus et al., 2009b; Jesus et al., 2010).

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